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# High Performance Computing Techniques in Finance

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CORPORATES & MARKETS

## Introduction

- Focus on techniques to enhance and tune performance on a given machine
- Geared towards C++ but concepts should be language agnostic
- 2 main techniques presented:
  - -Vectorised instructions
  - -Efficient payoff languages
- We do NOT discuss distributed computing concepts
  - -These are orthogonal to this presentation

# **Content Of Vectorised Operations**

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#### What are vectorised operations? Part I

- SIMD Single Instruction Multiple Data
- The same operation is performed upon multiple pieces of data in one "instruction"

double scalarExp( double x);
vector<double> vectorExp( const vector<double> & x );

- The scalar version operates upon one input vector operates upon multiple data
- The naïve implementation of vectorised version just loops over scalar version
- Of course proper implementations are cleverer and faster
- Best case is same speed as the scalar operation (and this is possible!)

#### Acronyms everywhere...

• SIMD – Single Instruction Multiple Data

-as explained

#### SSE – Streaming SIMD Extensions

-an explicit implementation of a SIMD instruction set

#### • SSE2, SSE3, SSSE3, SSE4, SSE5

-Enhancements to SSE

#### • MMX, 3DNow!

-Early implementations of SIMD, now superseded by SSE and descendents

• BLAS – Basic Linear Algebra Subprograms

-An API specification of some basic operations

## What is **BLAS**?

- BLAS is a set of common linear algebra operations
- It is split into 3 levels:
  - -Level1 consists of vector-vector operations eg dotProduct
  - -Level2 consists of matrix-vector operations eg matrixTimesVector
  - -Level3 consists of matrix-matrix operations eg matrixTimesMatrix
- Since the basic elements are vectors and matrices...
- ...any implementation of BLAS can benefit from use of vectorised instructions
- So from now on we only refer to vectorised instructions and assume this subsumes BLAS

## **Example BLAS**

- In the example below one can see the vector nature of BLAS straight away
- The explicit loop pointwise over vector elements is replaced by one simple function call

#### **Generic implementation**

```
double dotProduct(int n, double * x, double * y)
```

```
double returnValue = 0.0;
```

```
for(int i = 0 ; i < n ; ++i)
returnValue += x[i]*y[i];
```

```
return returnValue;
```

#### **BLAS** implementation

double dotProduct(int n, double \* x, double \* y)

```
return BLAS::dotProduct(n,x,y);
```

#### How to benefit from vectorised operations

• Analysis showed that a lot of time is spent in

#### -Linear algebra to generate Monte Carlo Paths for Brownian motion

- Local volatility for a high dimensional trade: a lot of matrix multiplication to correlate gaussian random variables
- Full factor BGM: a lot of vector operations for path construction

#### -Black Scholes formula to calibrate **Stochastic Volatility** and **Jump Diffusion**

- For each path NxM Black Scholes Formulae are computed
- N = number of times ; M = number of strikes ie N & M span the vol surface

#### **CPU Registers Part I**

#### • CPU Registers

-The CPU uses data registers to hold data(!)

-Data might be integers, floats, bit sets

-Access to these registers is extremely fast – the fastest memory available for access by the CPU

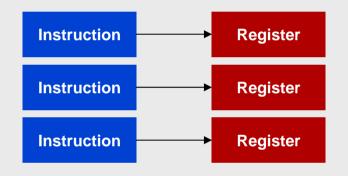
-CPU instructions act on these registers (and possibly store results in them)

-However registers are few and far between

-Compilers deal with the job of allocating registers and moving data between main memory and the registers (or rather producing code which does this)

## **CPU** architecture methods

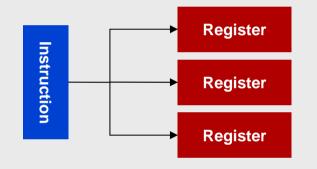
• SISD – Single Instruction Single Data



- Individual instructions act on individual data (held in registers)
- Implemented by the scalar FPU for example

## **CPU** architecture methods (cont.)

• SIMD – Single Instruction Multiple Data



- The same instruction acts on multiple data (held in registers)
- First made popular with supercomputers in 80's and 90's for example

## **CPU Registers Part II**

- Registers come in various sizes eg 32 bit, 64 bit, 128 bit
- Vectorised operations in fact operate upon one register "packed" with data
   Eg a 128 bit register could be filled with:
  - 2 doubles (8 bytes each) (8 bytes = quadword)
  - 4 floats (4 bytes each) (4 bytes = dword)
  - 2 long integers (8 bytes each)
  - 4 integers (4 bytes each)
  - 8 integers (2 bytes each) (2 bytes = word)
  - 16 integers (1 byte each)

#### Anatomy of a vectorised instruction

- Consider the assembler instruction to add contents of the 128 bit registers xmm0 and xmm1 (populated with packed double data) and store the result in xmm0 (as packed double data)
  - addpd xmm0, xmm1



#### How to implement these instructions? I

- Standalone assembly
  - -Pros
    - The fastest code and best flexibility possible short of writing machine code
  - -Cons
    - Too complicated!
    - Lots of expertise to write. Not reusable. Hard to maintain.
- Inline assembly embedded into C/C++
  - -Easy to use encapsulated functions. But Cons as before...
  - -Lots of expertise to write and hard to maintain

#### How to implement these instructions? II

- Intrinsic Functions
  - -These are compiler/vendor dependent

-They are similar to inline functions in sense that code is embedded directly into point of use rather than a function call

-Better than inline though since the machine code is generated directly; often platform specific

-The SSE2 instruction set is available in the Visual Studio compiler as a set of intrinsic functions

-However the same problems remain – to code these requires similar knowledge of the instruction set

#### How to implement these instructions? III

• 3<sup>rd</sup> Party Libraries

-Pros

- In effect someone else has done the hard work for you using some combination of the methods mentioned in the previous slides
- Maintenance is by the library vendor
- Functions should be in a nice easy to use form

-Cons

- Dependent on a black box solution from an external provider

#### How to implement these instructions? (cont.)

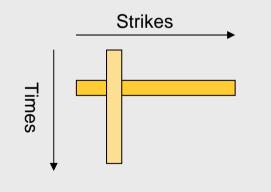
```
• Example of inline assembly
```

```
-Each of x and y contain 2 doubles and returns (x[1]+y[1], x[2]+y[2]) as 2 doubles
```

```
void add( double * x, double *y, double * returnValue )
{
    asm
    {
        movapd xmm0, [x]
        movapd xmm1, [y]
        addpd xmm0, xmm1
        movapd [returnValue], xmm0
    }
}
```

## Worked example I

- Monte Carlo calibration of a model (such as a stochastic volatility model) requires valuation of the calibration products on each path.
- Such a calibration product may be a European Option
- The number of European Options needed to span the volatility surface can be large can this benefit from vectorised operations?
- The number of European Options will be numberOfStrikes x numberOfTimes
- So we can vectorise in 2 possible ways:
  - -Fix a strike and have a vector of times
  - -Fix a time and have a vector of strikes
- Only trial and error will reveal quickest
- We choose to fix a time



#### Worked example I (continued)

- We now need to consider how to vectorise a Black Scholes formula
- Central to the Black Scholes formula is evaluation of the cumulative normal distribution Φ(z).

 $\Box \Phi(z) = 0.5[1 + erf(z/2^{1/2})]$ 

- Some vectorised libraries have an implementation of erf(z)
- Simple to extend and vectorise the Black Scholes formula for multiple strikes at fixed time and forward

```
Generic implementation
```

```
double cumNormDist(double z)
```

ł

```
return 0.5*(1.0+erf(z*ONE_OVER_SQRT_TWO));
```

#### **Vectorised implementation**

```
void cumNormDist(int n, double * z)
```

```
BLAS::L1::scale(n,z,ONE_OVER_SQRT_TWO);
SIMD::erf(n,z,z);
SIMD::add(n,VECTOR_OF_ONES,z,z);
BLAS::L1::scale(n,z,0.5);
```

#### Worked example I: Results

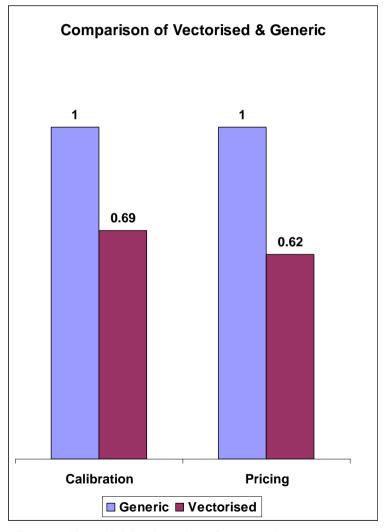
#### **Specifications**

- -2 factor Stochastic Vol Model
- -19 strikes for pricing model example
- -15 strikes for calibration model example
- -(scales linearly in times)

#### Comments

- -Significant speed gains possible
- -Mostly due to vectorised versions of complex mathematical functions rather than simple vectorisation functions such as BLAS

-Calibration gives slightly less improvement than Pricing since calibration involves many other overheads



Source: Financial Engineering, Commerzbank

## Worked example II

- A full factor BGM model has a high number of factors
- Each factor has lognormal type dynamics (with state dependent drift)
- Also a large number of matrix multiplications for correlated gaussians
- Prototypical dynamics for the i<sup>th</sup> Libor L<sub>i</sub> are of the form:

 $L_i(t) = \exp(drift_i(t) - 0.5 sigma_squared_i(t) + W_i(t))$ 

- Vectorisation proceeds as in example I but in two places:
  - -Vectorise the matrix multiplications of the correlated gaussians
  - -Vectorise the above dynamics using simple BLAS type routines for the addition and scaling of vectors and a vectorised version of exponential.

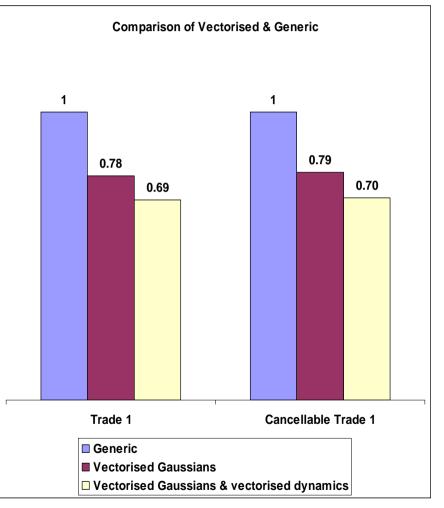
#### Worked example II: Results

#### • Specifications

- 40y BGM model, Libor\_3M underlying
- Trade 1 is a Ratchet Range Accrual, 6 month periods, with weekly observation frequency

#### Comments

- Again significant improvements observed
- Approximately two thirds of overall improvement due to matrix multiplies
- One third due to vectorised functions
- Testing revealed simple vectorisation of dynamics made very little contribution to the last one third



Source: Financial Engineering, Commerzbank

#### Conclusions

#### • Pros:

- Faster! But how much is really code, CPU and problem dependent
- Cons:
  - Penalty for low dimensionality (use at least for size 8)
  - Can be harder to read & maintain
  - Not all math operations available: need of many temporary vectors
    - (e.g. add 5 to every entry in a vector: need **vector of ones**)
  - Is it portable?
  - Mitigated by fact that many financial institutions work in controlled environments with fixed architectures and CPUs
- A useful tool but needs careful use and application!

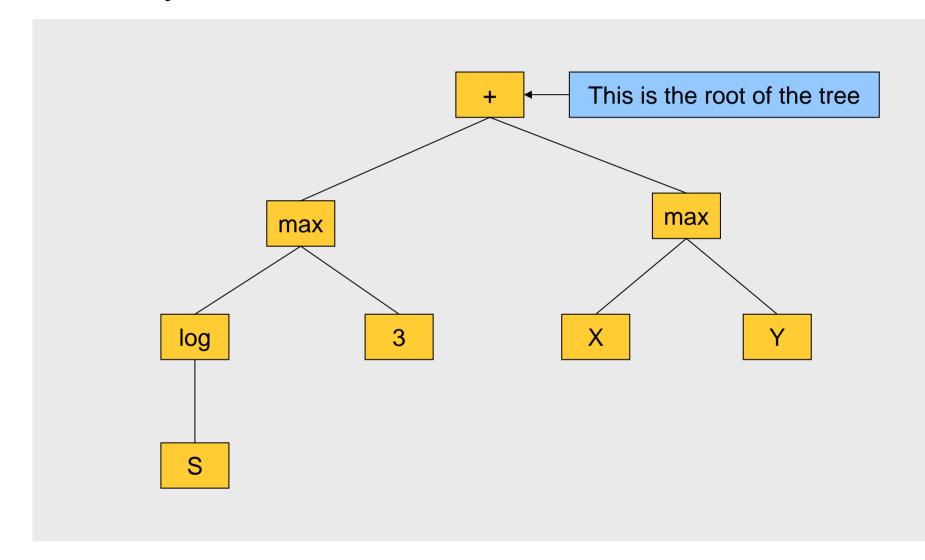
# **Content of Payoff Languages**

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#### **Payoff languages in a financial library**

- From a string containing the textual description of a mathematical function, it is possible to dynamically (i.e. at runtime) generate a data structure representing it.
- Without limitation, we will confine ourselves to a case where there is only 1
  payment, depending upon the values of an underlying called S and some extra
  variables X and Y
  - Payoff(S) = Max(Log(S), 3) + Max(X, Y)
- A very common implementation of this structure is a **tree**

## **Abstract Syntax Tree**



## **Description of a node**

- Node Fun
- Children

Function

Arguments

- A node without children (i.e. a leaf) is a **number** 
  - 5.6
  - X
  - Value of EuroStoxx50
- Every node has a function that returns its value (after valuing all arguments)
- To value the tree, just call value on the root

## **Pros / Cons of AST**

- Pros
  - Many
- Cons
  - It depends heavily on polymorphism
    - virtual functions (in C++)
    - Calls via function pointer (in C)
- For each path and for each node a virtual function is called
  - The pipeline stalls
  - BTB useless because target of jumps does not depend on **code location**, but on the **location in the tree**

Branch Target Buffer is a map in the CPU [address of code -> destination of jump]

## But...

- The elements of the tree **do not change** once the tree is built (i.e. their dynamic types are **constant**)
  - If node types were path dependent, this approach would not be possible
- Given a **position in the tree**, the virtual function called is the **same** for each path
- In the following we are going to make more explicit the link between position in the tree and the function called
- Then we will be able to **tell the CPU** that information

#### **Reverse Polish Notation**

- A tree is inherently written in Prefix notation
- We want to transform it to **Postfix** notation
- From

Max(Log(S), 3) + Max(X, Y)

• To

S, Log, 3, Max, X, Y, Max, +

• This can be obtained by traversing in postorder the tree.

#### **Postorder traversal**

• Definition

{

}

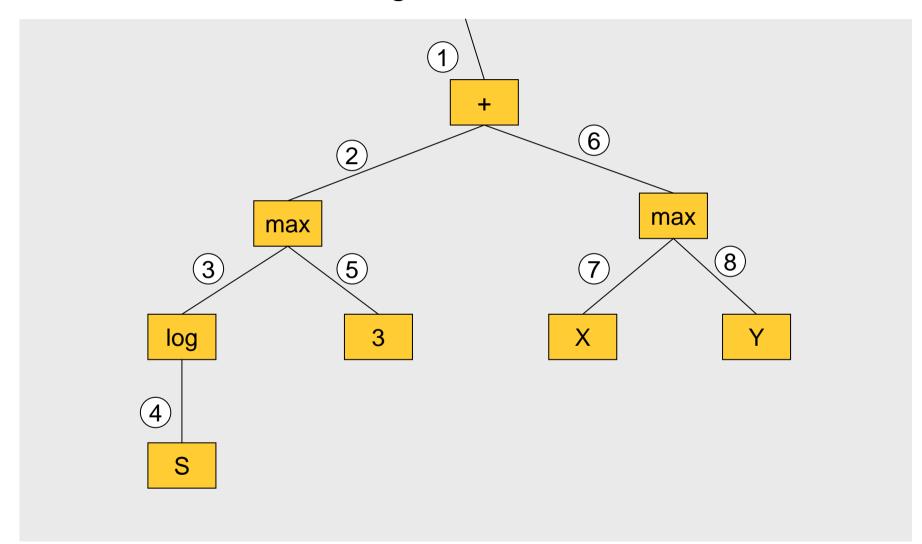
```
PostTraverse(Node a)
```

```
for each child c: PostTraverse(c)
```

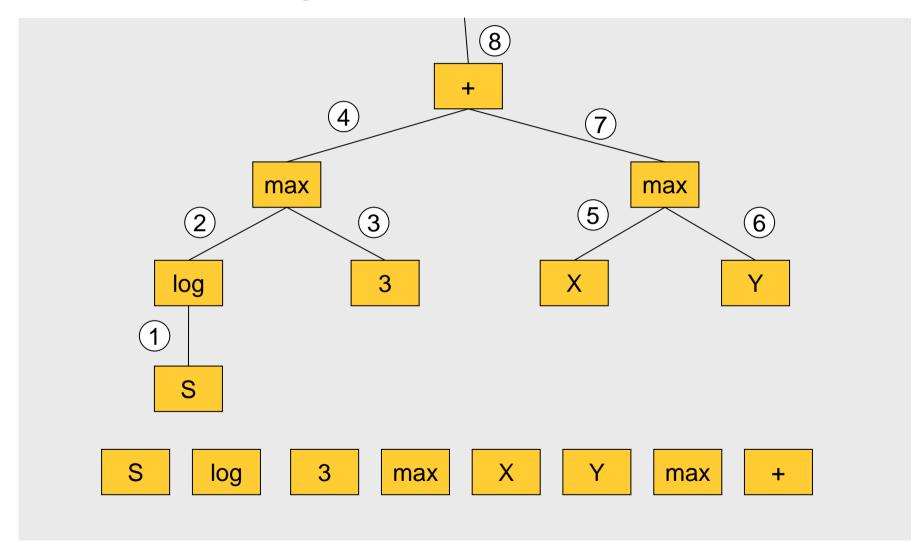
Do something about yourself (e.g. **print function name**)

- PostTraverse(root)
- This can be seen as writing in a linear sequence the names of the nodes in the order they return from the value function.

# Tree valuation: order of *calling* value



# **RPN: order of** *returning* from value

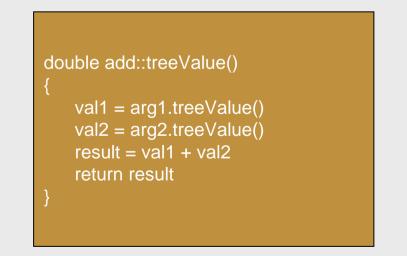


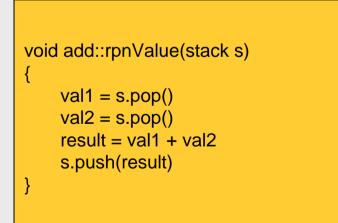
#### Pseudo code

```
postTraverse(Node a, vector<Node> v)
{
       for each child c: postTraverse(c)
       v.push(this)
}
. . . . .
vector<Node> linearTree
postTraverse(root)
. . . . .
```

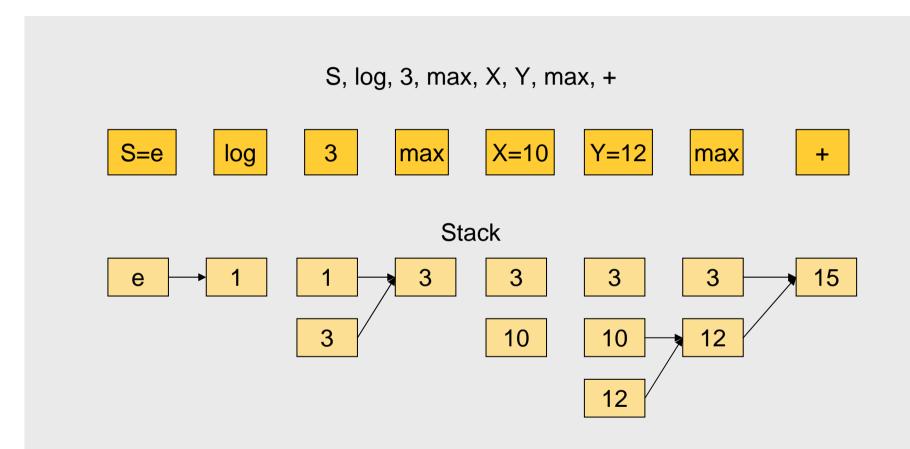
#### **RPN calculator: we need a stack**

- In a tree valuation, a function values its arguments
- In postfix notation, a function is valued after its arguments.
- When a node is *rpnValued* its arguments have to be **available**, **used** and **deleted**.
- A stack is the best candidate for this job





## **Example of stack based valuation**



Every block must **pop ALL** (if any) its arguments and **push ONE** result

# **RPN valuation: pseudo code**

```
double valuePayoff(vector<Node> nodes)
{
         stack s
         for (int i = 0; i < nodes.size())</pre>
         ł
                   nodes[i].rpnValue(s)
         assert(s.size() == 1)  << not present in the tree</pre>
         return s[0]
```

rpnValue is still a virtual function!

## However...

• The association of types (i.e. address of the virtual functions) with loop iteration is clear and more evident than in the tree

- nodes[0] is always of type Stock
- nodes[1] is always of type Log
- nodes[2] is always of type DoubleConstant

- .....

How can we communicate it to the CPU?

## ... we just unroll the loop!

 In order to tell the CPU about the type of the nodes we can simply unroll the loop and static\_cast each node

```
double valuePayoff(vector<Node> nodes)
{
    stack s
    static_cast<Stock> (nodes[0]).non_virtual_rpn_value(s)
    static_cast<Log> (nodes[1]).non_virtual_rpn_value(s)
    ....
    static_cast<Add> (nodes[7]).non_virtual_rpn_value(s)
    return s[0]
}
```

## We need to compile the code again

- But this can only done at **runtime** (when we have knowledge of the tree).
- There are at least 2 solutions:
  - Write C++ code to a file, call the compiler and dynamically load the DLL
  - Manually generate the machine code
- Can I find a compiler / assembler that I can link to my library?

## Machine code (in small doses)

- This is not as scary as it sounds because we only need to call functions like static\_cast<Stock>(nodes[0]).non\_virtual\_rpn\_value(s)
- Where the only differences are 2 pointers
  - The object's this (in Visual Studio passed in ECX)
  - The address of the function to call

FF 74 24 08	push	dword ptr [esp+8]
B9 <b>50 3F 9A 1B</b>	mov	ecx,1B9A3F50h
E8 20 C0 F0 11	call	Stock::non_virtual_rpn_value (11F0C020h)
FF 74 24 08	push	dword ptr [esp+8]
B9 <b>70 44 9A 1B</b>	mov	ecx, <b>1B9A4470h</b>
E8 20 B6 F0 11	call	Log:: non_virtual_rpn_value ( <b>11F0B620h</b> )

C3

ret

## **Pros / Cons of the RPN & compiled code**

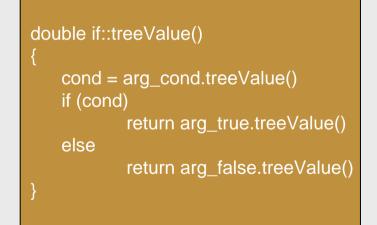
- Cons
  - Extra complexity (whether calling a compiler or managing machine code)
  - Hard to handle functions that conditionally value their arguments
     (e.g. IF, logical operator, variable length loops)
  - Machine code: Harder to port to different CPUs and compilers
- Pros
  - It can coexist with tree valuation
  - No virtual functions call
  - The machine code is self contained
  - Compiler can **inline** most of the functions (+,-,max,log.....)
  - Given the limitations of the language, there are no branch mispredictions
  - Therefore more CPU resources available to the rest of the application
  - Potentially allows for more **parallelization** (e.g. ClearSpeed hardware)

## **Example of IF statement**

• Original expression:

```
3 + IF(X > 0, return X + Y, else Z - 6)
```

RPN notation



When we get to the IF block, both cases **have already been valued** (i.e. they are already in the stack)

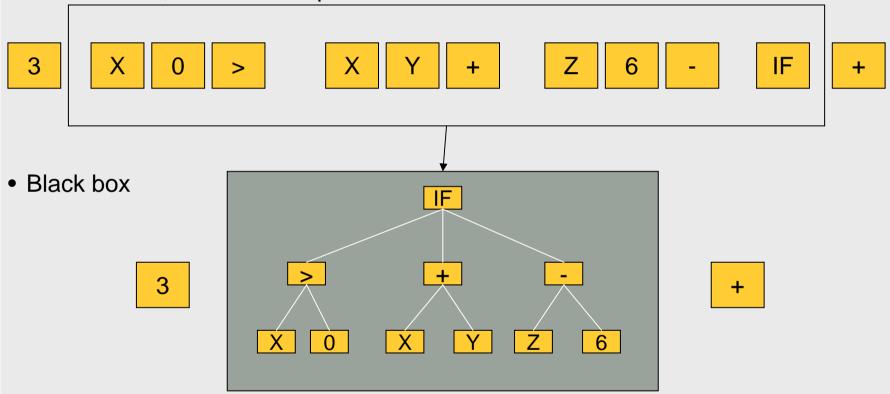
## How to solve the IF case

- However we feel that an IF function is an almost essential feature of any payoff language
- There are a few solutions
  - We can treat IF as a black box and revert to the tree valuation We lose all benefits of the compilation
  - We can value both arguments and then select the correct one Best solution, especially for trivial cases. Code is still branch-free. Not possible when functions have side effects.
  - 3. Emit more **complex** code

Allows to handle more sophisticated cases (e.g. loops)

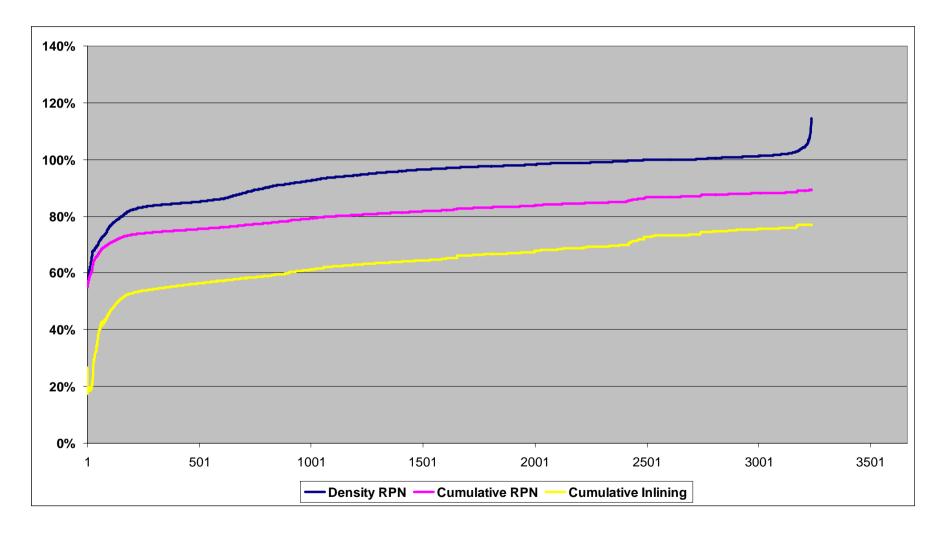
# IF as a black box

• As a fallback, for more complex cases we can revert to the tree valuation



• The same can be applied to any other complicated function (e.g. loops)

# **Comparison Tree vs RPN valuation**



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Source: Financial Engineering, Commerzbank

## **Results and conclusions**

- We have implemented an internal compiler to machine code
- Initial tests on a large (~3000) set of equity trades have shown speed up of about 11%
- More (up to 25%) can be gained with more aggressive inlining of trivial operations
- No change to the pricing / risk / farm infrastructure since this solution is self contained in the library
- Very important to **encapsulate** complexity in order to keep code usable, readable and maintainable
- Easy to implement tree and RPN methods side by side
- Important to run over a wide range of trades to profile and tune

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