

# High Performance <br> Computing Techniques in Finance 

Andrea Odetti
Sanjeev Shukla

## Introduction

- Focus on techniques to enhance and tune performance on a given machine
- Geared towards C++ but concepts should be language agnostic
- 2 main techniques presented:
-Vectorised instructions
-Efficient payoff languages
- We do NOT discuss distributed computing concepts
-These are orthogonal to this presentation


## Content Of Vectorised Operations

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## What are vectorised operations? Part I

- SIMD - Single Instruction Multiple Data
- The same operation is performed upon multiple pieces of data in one "instruction"
double scalarExp( double x);
vector<double> vectorExp( const vector<double> \& x);
- The scalar version operates upon one input - vector operates upon multiple data
- The naïve implementation of vectorised version just loops over scalar version
- Of course proper implementations are cleverer and faster
- Best case is same speed as the scalar operation (and this is possible!)


## Acronyms everywhere...

- SIMD - Single Instruction Multiple Data
-as explained
- SSE - Streaming SIMD Extensions
-an explicit implementation of a SIMD instruction set
- SSE2, SSE3, SSSE3, SSE4, SSE5
-Enhancements to SSE
- MMX, 3DNow!
-Early implementations of SIMD, now superseded by SSE and descendents
- BLAS - Basic Linear Algebra Subprograms
-An API specification of some basic operations


## What is BLAS?

- BLAS is a set of common linear algebra operations
- It is split into 3 levels:
-Level1 consists of vector-vector operations eg dotProduct
-Level2 consists of matrix-vector operations eg matrixTimesVector
-Level3 consists of matrix-matrix operations eg matrixTimesMatrix
- Since the basic elements are vectors and matrices...
- ...any implementation of BLAS can benefit from use of vectorised instructions
- So from now on we only refer to vectorised instructions and assume this subsumes BLAS


## Example BLAS

- In the example below one can see the vector nature of BLAS straight away
- The explicit loop pointwise over vector elements is replaced by one simple function call

```
Generic implementation
double dotProduct(int n, double * x, double * y)
{
    double returnValue = 0.0;
    for(int i=0; i < n ; ++i)
        returnValue += x[i]*y[i];
    return returnValue;
}
```

```
BLAS implementation
double dotProduct(int n, double * x, double * y)
{
    return BLAS::dotProduct(n,x,y);
}
```


## How to benefit from vectorised operations

- Analysis showed that a lot of time is spent in
-Linear algebra to generate Monte Carlo Paths for Brownian motion
- Local volatility for a high dimensional trade: a lot of matrix multiplication to correlate gaussian random variables
- Full factor BGM: a lot of vector operations for path construction
-Black Scholes formula to calibrate Stochastic Volatility and Jump Diffusion
- For each path NxM Black Scholes Formulae are computed
- $N=$ number of times ; $M=$ number of strikes ie $N \& M$ span the vol surface


## CPU Registers Part I

## - CPU Registers

-The CPU uses data registers to hold data(!)
-Data might be integers, floats, bit sets
-Access to these registers is extremely fast - the fastest memory available for access by the CPU
-CPU instructions act on these registers (and possibly store results in them)
-However registers are few and far between
-Compilers deal with the job of allocating registers and moving data between main memory and the registers (or rather producing code which does this)

## CPU architecture methods

- SISD - Single Instruction Single Data

- Individual instructions act on individual data (held in registers)
- Implemented by the scalar FPU for example


## CPU architecture methods (cont.)

- SIMD - Single Instruction Multiple Data

- The same instruction acts on multiple data (held in registers)
- First made popular with supercomputers in 80 's and 90 's for example


## CPU Registers Part II

- Registers come in various sizes eg 32 bit, 64 bit, 128 bit
- Vectorised operations in fact operate upon one register "packed" with data
-Eg a 128 bit register could be filled with:
- 2 doubles
(8 bytes each)
( 8 bytes = quadword)
- 4 floats
( 4 bytes each) ( 4 bytes $=$ dword $)$
- 2 long integers
(8 bytes each)
- 4 integers
(4 bytes each)
- 8 integers
(2 bytes each)
( 2 bytes = word )
- 16 integers
(1 byte each)


## Anatomy of a vectorised instruction

- Consider the assembler instruction to add contents of the 128 bit registers $\mathrm{xmm0}$ and xmm1 (populated with packed double data) and store the result in xmm0 (as packed double data)
- addpd xmm0, xmm1



## How to implement these instructions? I

- Standalone assembly
-Pros
- The fastest code and best flexibility possible short of writing machine code
-Cons
- Too complicated!
- Lots of expertise to write. Not reusable. Hard to maintain.
- Inline assembly embedded into $\mathrm{C} / \mathrm{C}++$
-Easy to use encapsulated functions. But Cons as before...
-Lots of expertise to write and hard to maintain


## How to implement these instructions? II

- Intrinsic Functions
-These are compiler/vendor dependent
-They are similar to inline functions in sense that code is embedded directly into point of use rather than a function call
-Better than inline though since the machine code is generated directly; often platform specific
-The SSE2 instruction set is available in the Visual Studio compiler as a set of intrinsic functions
-However the same problems remain - to code these requires similar knowledge of the instruction set


## How to implement these instructions? III

- $3^{\text {rd }}$ Party Libraries


## -Pros

- In effect someone else has done the hard work for you using some combination of the methods mentioned in the previous slides
- Maintenance is by the library vendor
- Functions should be in a nice easy to use form
-Cons
- Dependent on a black box solution from an external provider


## How to implement these instructions? (cont.)

- Example of inline assembly
- Each of $x$ and $y$ contain 2 doubles and returns ( $x[1]+y[1], x[2]+y[2])$ as 2 doubles

```
void add(double * x, double *y, double * returnValue )
```

\{
asm
\{
movapd xmm0, $[\mathrm{x}]$
movapd xmm1, [y]
addpd xmm0, xmm1
movapd [returnValue] , xmm0
\}
\}

## Worked example I

- Monte Carlo calibration of a model (such as a stochastic volatility model) requires valuation of the calibration products on each path.
- Such a calibration product may be a European Option
- The number of European Options needed to span the volatility surface can be large - can this benefit from vectorised operations?
- The number of European Options will be numberOfStrikes x numberOfTimes
- So we can vectorise in 2 possible ways:
-Fix a strike and have a vector of times
-Fix a time and have a vector of strikes
- Only trial and error will reveal quickest
- We choose to fix a time



## Worked example I (continued)

- We now need to consider how to vectorise a Black Scholes formula
- Central to the Black Scholes formula is evaluation of the cumulative normal distribution $\Phi(\mathrm{z})$.
$\square \Phi(z)=0.5\left[1+\operatorname{erf}\left(z / 2^{1 / 2}\right)\right]$
- Some vectorised libraries have an implementation of erf(z)
- Simple to extend and vectorise the Black Scholes formula for multiple strikes at fixed time and forward

```
Generic implementation
double cumNormDist(double z)
{
    return 0.5*(1.0+erf(z*ONE_OVER_SQRT_TWO));
}
```

```
Vectorised implementation
void cumNormDist(int n, double * z)
{
    BLAS::L1::scale(n,z,ONE_OVER_SQRT_TWO);
    SIMD::erf(n,z,z);
    SIMD::add(n,VECTOR_OF_ONES,z,z);
    BLAS::L1::scale(n,z,0.5);
}
```


## Worked example I: Results

## Specifications

-2 factor Stochastic Vol Model
-19 strikes for pricing model example
-15 strikes for calibration model example -(scales linearly in times)

## Comments

-Significant speed gains possible -Mostly due to vectorised versions of complex mathematical functions rather than simple vectorisation functions such as BLAS
-Calibration gives slightly less improvement than Pricing since calibration involves many other overheads


Source: Financial Engineering, Commerzbank

## Worked example II

- A full factor BGM model has a high number of factors
- Each factor has lognormal type dynamics (with state dependent drift)
- Also a large number of matrix multiplications for correlated gaussians
- Prototypical dynamics for the $i^{\text {th }}$ Libor $L_{i}$ are of the form:
$L_{i}(t)=\exp \left(\operatorname{drift}_{\mathrm{i}}(\mathrm{t})-0.5\right.$ sigma_squared $\left._{\mathrm{i}}(\mathrm{t})+\mathrm{W}_{\mathrm{i}}(\mathrm{t})\right)$
- Vectorisation proceeds as in example I but in two places:
-Vectorise the matrix multiplications of the correlated gaussians
-Vectorise the above dynamics using simple BLAS type routines for the addition and scaling of vectors and a vectorised version of exponential.


## Worked example II: Results

- Specifications
- 40y BGM model, Libor_3M underlying
- Trade 1 is a Ratchet Range Accrual, 6 month periods, with weekly observation frequency
- Comments
- Again significant improvements observed
- Approximately two thirds of overall improvement due to matrix multiplies
- One third due to vectorised functions
- Testing revealed simple vectorisation of dynamics made very little contribution to the last one third


Source: Financial Engineering, Commerzbank

## Conclusions

- Pros:
- Faster! But how much is really code, CPU and problem dependent
- Cons:
- Penalty for low dimensionality (use at least for size 8)
- Can be harder to read \& maintain
- Not all math operations available: need of many temporary vectors
(e.g. add 5 to every entry in a vector: need vector of ones)
- Is it portable?
- Mitigated by fact that many financial institutions work in controlled environments with fixed architectures and CPUs
- A useful tool but needs careful use and application!


## Content of Payoff Languages

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## Payoff languages in a financial library

- From a string containing the textual description of a mathematical function, it is possible to dynamically (i.e. at runtime) generate a data structure representing it.
- Without limitation, we will confine ourselves to a case where there is only 1 payment, depending upon the values of an underlying called $S$ and some extra variables $X$ and $Y$

$$
\text { - Payoff(S) }=\operatorname{Max}(\log (S), 3)+\operatorname{Max}(X, Y)
$$

- A very common implementation of this structure is a tree


## Abstract Syntax Tree



## Description of a node

- Node
- Children

Function
Arguments

- A node without children (i.e. a leaf) is a number
- 5.6
- X
- Value of EuroStoxx50
- Every node has a function that returns its value (after valuing all arguments)
- To value the tree, just call value on the root


## Pros / Cons of AST

- Pros
- Many
- Cons
- It depends heavily on polymorphism
- virtual functions (in C++)
- Calls via function pointer (in C)
- For each path and for each node a virtual function is called
- The pipeline stalls
- BTB useless because target of jumps does not depend on code location, but on the location in the tree
Branch Target Buffer is a map in the CPU [address of code -> destination of jump]


## But...

- The elements of the tree do not change once the tree is built (i.e. their dynamic types are constant)
- If node types were path dependent, this approach would not be possible
- Given a position in the tree, the virtual function called is the same for each path
- In the following we are going to make more explicit the link between position in the tree and the function called
- Then we will be able to tell the CPU that information


## Reverse Polish Notation

- A tree is inherently written in Prefix notation
- We want to transform it to Postfix notation
- From

$$
\operatorname{Max}(\log (S), 3)+\operatorname{Max}(X, Y)
$$

- To
S, Log, 3, Max, X, Y, Max, +
- This can be obtained by traversing in postorder the tree.


## Postorder traversal

- Definition

PostTraverse(Node a)
\{
for each child c: PostTraverse(c)
Do something about yourself (e.g. print function name)
\}

- PostTraverse(root)
- This can be seen as writing in a linear sequence the names of the nodes in the order they return from the value function.


## Tree valuation: order of calling value



RPN: order of returning from value


## Pseudo code

```
postTraverse(Node a, vector<Node> v)
{
    for each child c: postTraverse(c)
    v.push(this)
}
```

vector<Node> linearTree
postTraverse(root)

## RPN calculator: we need a stack

- In a tree valuation, a function values its arguments
- In postfix notation, a function is valued after its arguments.
- When a node is rpnValued its arguments have to be available, used and deleted.
- A stack is the best candidate for this job



## Example of stack based valuation



Every block must pop ALL (if any) its arguments and push ONE result

## RPN valuation: pseudo code

```
double valuePayoff(vector<Node> nodes)
{
        stack s
        for (int i = 0; i < nodes.size())
        {
        nodes[i].rpnValue(s)
        }
        assert(s.size() == 1) << not present in the tree
    return s[0]
}
```

rpnValue is still a virtual function!

## However...

- The association of types (i.e. address of the virtual functions) with loop iteration is clear and more evident than in the tree
- nodes[0] is always of type Stock
- nodes[1] is always of type Log
- nodes[2] is always of type DoubleConstant
- .....
- How can we communicate it to the CPU?
... we just unroll the loop!
- In order to tell the CPU about the type of the nodes we can simply unroll the loop and static_cast each node

```
double valuePayoff(vector<Node> nodes)
{
    stack s
    static_cast<Stock> (nodes[0]).non_virtual_rpn_value(s)
    static_cast<Log> (nodes[1]).non_virtual_rpn_value(s)
    static_cast<Add> (nodes[7]).non_virtual_rpn_value(s)
    return s[0]
}
```


## We need to compile the code again

- But this can only done at runtime (when we have knowledge of the tree).
- There are at least 2 solutions:
- Write C++ code to a file, call the compiler and dynamically load the DLL
- Manually generate the machine code
- Can I find a compiler / assembler that I can link to my library?


## Machine code (in small doses)

- This is not as scary as it sounds because we only need to call functions like static_cast<Stock>(nodes[0]).non_virtual_rpn_value(s)
- Where the only differences are 2 pointers
- The object's this (in Visual Studio passed in ECX)
- The address of the function to call

| FF 74 24 08 | push | dword ptr [esp+8] |
| :--- | :--- | :--- |
| B9 50 3F 9A 1B | mov | ecx,1B9A3F50h |
| E8 20 C0 F0 11 | call | Stock::non_virtual_rpn_value (11F0C020h) |
|  |  |  |
| FF 74 24 08 | push | dword ptr [esp+8] |
| B9 70 44 9A 1B | mov | ecx,1B9A4470h |
| E8 20 B6 F0 11 | call | Log:: non_virtual_rpn_value (11F0B620h) |

## Pros / Cons of the RPN \& compiled code

- Cons
- Extra complexity (whether calling a compiler or managing machine code)
- Hard to handle functions that conditionally value their arguments (e.g. IF, logical operator, variable length loops)
- Machine code: Harder to port to different CPUs and compilers
- Pros
- It can coexist with tree valuation
- No virtual functions call
- The machine code is self contained
- Compiler can inline most of the functions (+,-,max,log.....)
- Given the limitations of the language, there are no branch mispredictions
- Therefore more CPU resources available to the rest of the application
- Potentially allows for more parallelization (e.g. ClearSpeed hardware)


## Example of IF statement

- Original expression:

$$
3+\operatorname{IF}(X>0, \text { return } X+Y, \text { else } Z-6)
$$

- RPN notation


When we get to the IF block, both cases have already been valued (i.e. they are already in the stack)

## How to solve the IF case

- However we feel that an IF function is an almost essential feature of any payoff language
- There are a few solutions

1. We can treat IF as a black box and revert to the tree valuation We lose all benefits of the compilation
2. We can value both arguments and then select the correct one

Best solution, especially for trivial cases. Code is still branch-free.
Not possible when functions have side effects.
3. Emit more complex code

Allows to handle more sophisticated cases (e.g. loops)

## IF as a black box

- As a fallback, for more complex cases we can revert to the tree valuation

- The same can be applied to any other complicated function (e.g. loops)


## Comparison Tree vs RPN valuation



## Results and conclusions

- We have implemented an internal compiler to machine code
- Initial tests on a large ( $(3000)$ set of equity trades have shown speed up of about 11\%
- More (up to $25 \%$ ) can be gained with more aggressive inlining of trivial operations
- No change to the pricing / risk / farm infrastructure since this solution is self contained in the library
- Very important to encapsulate complexity in order to keep code usable, readable and maintainable
- Easy to implement tree and RPN methods side by side
- Important to run over a wide range of trades to profile and tune


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## Main Offices

Frankfurt
DLZ - Gebäude 2
Händlerhaus
Mainzer Landstraße 153
60327 Frankfurt
Germany
Phone: +49 6913644440

## London

60 Gracechurch Street
London, EC3V OHR
United Kingdom
Phone: +44 2076537000

Branches
Amsterdam
Strawinskylaan 2501
1077 ZZ Amsterdam
Netherland
Phone: +31 205574911
Budapest
Széchenyi rakpart 8
H-1054 Budapest
Hungary
Phone: +361 3748100
Brussels
Blvd Louis Schmidt 87
BE-1040 Brussels
Belgium
Phone: +32 27431866
Hong Kong
21/F, Hong Kong Club Building
3a Chater Road
Hong Kong
China
Phone: +852 28429666
Johannesburg
5 Keyes Avenue
2196 Johannesburg
South Africa
Phone: +27 113287600

| Luxembourg | Paris |
| :--- | :--- |
| 25, rue Edward Steichen | 23 rue de la Paix |
| 2540 Luxemburg | 75002 Paris |
| Luxembourg | France |
| Phone: +352 4779111 | Phone: +33 14494 1700 |
| Madrid | Prague |
| Ps. Castellana 110 | Jugoslavska 1 |
| 28046 Madrid | 120 21 Prague |
| Spain | Czech Republic |
| Phone: +34 91 572 4700 | Phone: +420 221 193 111 |
| Milan | Singapore |
| Via Cordusio 2 | 8 Shenton Way |
| 20123 Milan | Temasek Towers |
| Italy | Singapore 068811 |
| Phone: +39 02 725 961 | Singapore |
|  | Phone: +65 63110 000 |
| Moscow |  |
| Kadashevskaya naberezhnya 14/2 | Shanghai |
| 119017 Moscow | 25F, World Plaza |
| Russia | 855 Pudong South Road |
| Phone: +7 495 797 4800 | 200120 Shanghai |
|  | China |
| New York | Phone: +86 21 5836 6666 |
| 2 World Financial Center |  |
| 31st Floor |  |
| New York, NY 10281 |  |
| USA |  |
| Phone: +1 212 266 7200 |  |

